

**Overview** 

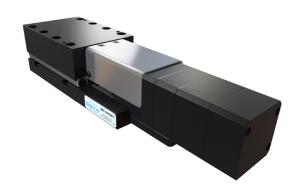
## Precision Linear Motion Platform

### **FEATURES**

- Compact Low-Profile Design
- 50mm Travel
- Zero backlash, precision ground

#### ball screws

- Optical limit switches with home
- Brushless Servo Motor
- Crossed Roller Bearings



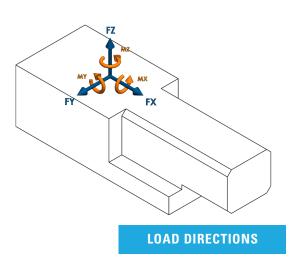
The MCS-BS Series stages are designed for a variety of applications. This compact low profile ball screw stage is built for high duty cycles and long life for laboratory, factory automation and semiconductor processing equipment. This stage has exceptional levels of flatness and straightness. The crossed roller bearings and a precision ground ball screw offer extremely smooth operation and velocity control. The MCS-BS Series stages can be stacked to create X, Y and Z motion. The stage can operate in any orientation and has an optional brake for added safety and the optional tooling plate is easily customized for different mounting options.



## **Motion Specifications**

## **Product Specifications**

Force X (N)	75
Force Y (N)	75
Force Z (N)	75
Flatness (µm)	4
Height (mm)	51
Length (mm)	260
Limit Switches	Yes
Linear Accuracy (µm)	10
Linear Encoder Resolution (µm)	0.125
Linear Repeatability (µm)	2
Linear Velocity (mm/s)	50
Moment X (N⋅m)	2
Moment Y (N⋅m)	2
Moment Z (N⋅m)	2
Moving Mass X (kg)	0.64
Pitch +/- (arc-sec)	12
Screw Lead (mm)	2
Stage Mass (kg)	1.7
Straigtness (µm)	4
Width (mm)	67
Yaw +/- (arc-sec)	10

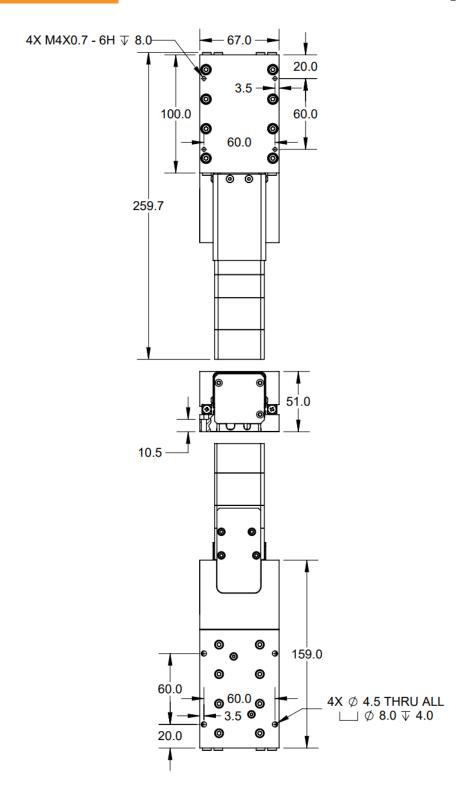


# Part Number Description

MCS	MCS Series
050	50mm Travel
BS	Ball Screw Drive
А	Brushless Servo Motor
Н	0.125µm Rotary Encoder
S	Standard Precision
D	Power-Off Brake
00	Standard Product (Call for custom)



## **Mechanical Specifications**

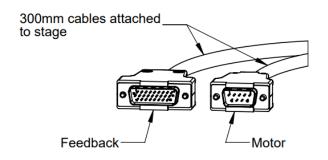






### **Electrical Pinout**

Feedback Connector (DSUB26HD MALE)	
PIN	NAME
1	+5V
2	A+
3	B+
4	RI+
5	LIM+
6	*
7	*
8	*
9	*
10	*
11	A-
12	B-
13	RI-
14	LIM-
15	*
16	*
17	*
18	*
19	GND
20	HALL A
21	HALL B
22	HALL C
23	HOME
24	*
25	*
26	*
* Reserved	



Motor Connector (DCLIDO MALE)		
Motor Connector (DSUB9 MALE)		
PIN	NAME	
1	*	
2	*	
3	*	
4	*	
5	*	
6	PHASE A	
7	PHASE B	
8	PHASE C	
9	*	
* Reserved		



## **Electrical Specifications**

Motor Specifications		
Motor Type	3 Φ Brushless DC	
BEMF Constant (V/KRPM)	1.88	
Electrical Time Constant (ms)	0.38	
Max Bus Voltage (VDC)	40	
Max Continuous Current (A)	3.0	
Motor Force Constant (N/A)	50.8	
Peak Current (A)	10.0	
Pin to Pin Inductance (mH)	0.55	
Pin to Pin Resistance (ohm)	1.51	
Poles per Revolution	6	

Brake Specifications		
Brake Type	Power Off Engaged	
Winding Voltage (VDC)	24.0	
Winding Current (A)	0.17	
Winding Resistance (Ohm)	138	

Feedback Specifications		
Supply Voltage (V)	5.0±10%	
Supply Current (mA)	250	
Encoder Feedback	Yes	
Encoder Type	Incremental	
Encoder Ouput	Square Wave Quadrature, RS-422 compatible, A,B,Z, Differential Pairs	
Encoder Resolution	8000 cts/mm	
Hall Switch Output	Open-Collector, No Pullup Resistor	
Hall Switch max current (mA)	-20	
Limit Switches	Yes	
Limit Switch Output Type	CMOS	
Limit Switch Output current (mA)	±20.0	
Home Switch	Yes	
Home Switch Output Type	смоѕ	
Home Switch Output current (mA)	±20.0	

A home switch is provided near center mechanical travel and a limit switch at each end of travel. The encoder will output one index pulse per revolution of the motor. This pulse is highly repeatable and can be used in coordination with the home switch to find an absolute position after power-up.

The limit switches will be pulled low throughout the travel range of the stage. The output will swing high at the end of travel and remain high until the mechanical limit of the stage is reached.