

**Overview** 

## Precision XY Motion Platform

### **FEATURES**

- Compact Low-Profile Design
- 50mm XY Travel
- Zero backlash, precision ground

#### ball screws

- Optical limit switches with home
- High resolution linear encoder
- Brushless servo motor drive
- Crossed Roller Bearings



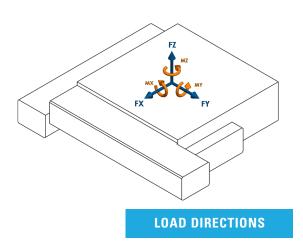
The CXY-BS series stages are designed for a variety of applications. This compact low profile ball screw stage is built for high duty cycles and long life and can attain high velocities for factory automation and semiconductor processing equipment. The CXY series offers extraordinary levels of orthogonality and parallelism resulting in high accuracy for combined axis motion. Recirculating ball linear ways and precision ground ball screws offer extremely smooth operation and velocity control. The XY stage can operate in any orientation and has optional brakes for added safety.



### **Motion Specifications**

## **Product Specifications**

| Encoder Output                 | A quad B, index |
|--------------------------------|-----------------|
| Force X (N)                    | 200             |
| Force Y (N)                    | 200             |
| Force Z (N)                    | 250             |
| Flatness (µm)                  | 4               |
| Height (mm)                    | 66              |
| Length (mm)                    | 247             |
| Limit Switches                 | Yes             |
| Linear Accuracy (µm)           | 5               |
| Linear Encoder Resolution (µm) | 0.1             |
| Linear Repeatability (µm)      | 0.5             |
| Linear Velocity (mm/s)         | 150             |
| Moment X (N·m)                 | 110             |
| Moment Y (N·m)                 | 110             |
| Moment Z (N·m)                 | 75              |
| Moving Mass X (kg)             | 4.04            |
| Moving Mass Y (kg)             | 1.26            |
| Orthogonality (arc-sec)        | 5               |
| Pitch +/- (arc-sec)            | 4               |
| Screw Lead (mm)                | 2               |
| Stage Mass (kg)                | 6.2             |
| Straigtness (µm)               | 4               |
| Width (mm)                     | 207             |
| Yaw +/- (arc-sec)              | 4               |

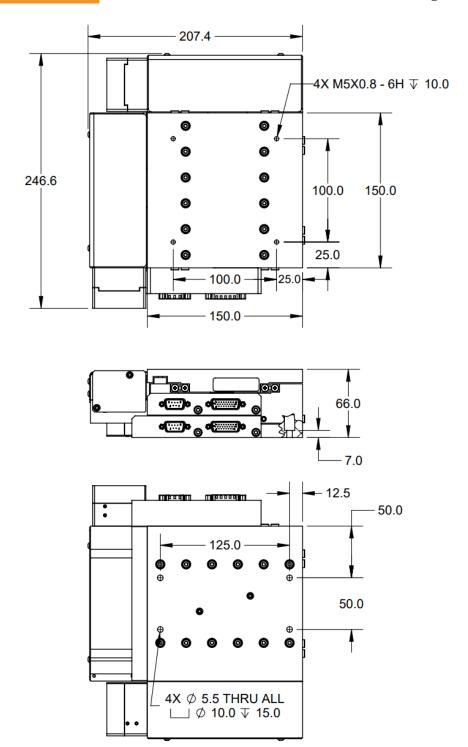


# Part Number Description

| CXY | CXY Series                            |
|-----|---------------------------------------|
| С   | No Aperture                           |
| 050 | 50mm Travel                           |
| BS  | Ball Screw Drive                      |
| А   | Brushless Servo Motor                 |
| М   | 0.1µm Linear SS Scale                 |
| Р   | High Precision                        |
| 0   | No Additional Options                 |
| 00  | Standard Product<br>(Call for custom) |



## **Mechanical Specifications**

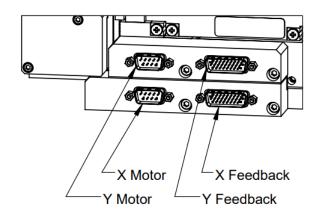






### **Electrical Pinout**

| Feedback Connector<br>(DSUB26HD MALE) |        |
|---------------------------------------|--------|
| PIN                                   | NAME   |
| 1                                     | +5V    |
| 2                                     | A+     |
| 3                                     | B+     |
| 4                                     | RI+    |
| 5                                     | LIM+   |
| 6                                     | *      |
| 7                                     | *      |
| 8                                     | *      |
| 9                                     | *      |
| 10                                    | *      |
| 11                                    | A-     |
| 12                                    | B-     |
| 13                                    | RI-    |
| 14                                    | LIM-   |
| 15                                    | *      |
| 16                                    | *      |
| 17                                    | *      |
| 18                                    | *      |
| 19                                    | GND    |
| 20                                    | HALL A |
| 21                                    | HALL B |
| 22                                    | HALL C |
| 23                                    | *      |
| 24                                    | *      |
| 25                                    | *      |
| 26                                    | *      |
| * Reserved                            |        |



| Motor Connector (DSUB9 MALE) |         |
|------------------------------|---------|
| PIN                          | NAME    |
| 1                            | *       |
| 2                            | *       |
| 3                            | *       |
| 4                            | *       |
| 5                            | *       |
| 6                            | PHASE A |
| 7                            | PHASE B |
| 8                            | PHASE C |
| 9                            | *       |
| * Reserved                   |         |



### **Electrical Specifications**

| Motor Specifications          |                  |  |
|-------------------------------|------------------|--|
| Motor Type                    | 3 Ф Brushless DC |  |
| BEMF Constant (V/KRPM)        | 1.88             |  |
| Electrical Time Constant (ms) | 0.38             |  |
| Max Bus Voltage (VDC)         | 40               |  |
| Max Continuous Current (A)    | 3.0              |  |
| Motor Force Constant (N/A)    | 50.8             |  |
| Peak Current (A)              | 10.0             |  |
| Pin to Pin Inductance (mH)    | 0.55             |  |
| Pin to Pin Resistance (ohm)   | 1.51             |  |
| Poles per Revolution          | 6                |  |

| 5.0±10%  |
|--|
| 200  |
| Yes  |
| Incremental  |
| Square Wave Quadrature, RS-422 compatible, A,B,Z, Differential Pairs |
| 10000 cts/mm   |
| Open-collector, no internal pullup resistor                          |
| -20  |
| Yes  |
| Open-collector, no internal pullup resistor                          |
| -20.0  |
| 0.8  |
|  |

The encoder will output one index pulse near center travel. This pulse is highly repeatable and can be used upon power-up to find an absolute position to use for further measurements.

Two limit switches are provided at the ends of travel. The limit switches will be pulled low throughout the travel range of the stage. The output will swing to high-impedance at the end of travel and remain high-impedance until the mechanical limit of the stage is reached.