## Precision Linear Motion Platform

## FEATURES

- High speed
-300mm Travel
- Precision ground ball screw drive
- Optical limit switches with home
- High resolution rotary encoder
- Recirculating ball linear ways
- Side seals

The LM2 Series stages are designed for a variety of applications. This compact low profile linear stage is built for high duty cycles and long life and attains high velocities for factory automation and semiconductor processing equipment. This stage has exceptional levels of accuracy, repeatability, flatness and straightness. Recirculating ball linear ways and the precision ground ball screw offer extremely smooth operation and velocity control. Side seals and a hard cover make it an excellent choice for dirty environments. The LM2 Series stages can be stacked to create XY motion.

## Product Specifications

| Encoder Output | A quad B, index |
| :---: | :---: |
| Force X (N) | 180 |
| Force $\mathrm{Y}(\mathrm{N})$ | 180 |
| Force Z (N) | 360 |
| Flatness ( $\mu \mathrm{m}$ ) | 10 |
| Height (mm) | 70 |
| Length (mm) | 592 |
| Limit Switches | Yes |
| Linear Accuracy ( $\mu \mathrm{m}$ ) | 15 |
| Linear Encoder Resolution ( $\mu \mathrm{m}$ ) | 0.125 |
| Linear Repeatability ( $\mu \mathrm{m}$ ) | 2 |
| Linear Velocity (mm/s) | 150 |
| Moment X (N•m) | 30 |
| Moment $\mathrm{Y}(\mathrm{N} \cdot \mathrm{m})$ | 30 |
| Moment Z (N•m) | 20 |
| Moving Mass X (kg) | 1.1 |
| Pitch +/- (arc-sec) | 12 |
| Screw Lead (mm) | 2 |
| Stage Mass (kg) | 5.94 |
| Straigtness ( $\mu \mathrm{m}$ ) | 10 |
| Width (mm) | 115 |
| Yaw +/- (arc-sec) | 12 |



## Part Number Description

| LM2 | LM2 Series |
| :--- | :--- |
| 300 | 300 mm Travel |
| BS | Ball Screw Drive |
| A | Brushless Servo Motor |
| H | $0.125 \mu \mathrm{~m}$ Rotary |
| S | Standard Precision |
| F | Side Seals |
| 00 | Standard Product <br> (Call for custom) |

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Mechanical Specifications


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Mounting Pattern


## LM2-300-BS-A-H-S-F-00

Feedback Connector
(DSUB26HD MALE)

| PIN | NAME |
| :--- | :--- |
| 1 | +5 V |
| 2 | A+ |
| 3 | B+ |
| 4 | RI+ |
| 5 | LIM + |
| 6 | * |
| 7 | * |
| 8 | * |
| 9 | * |
| 10 | A- |
| 11 | B- |
| 12 | RI- |
| 13 | LIM- |
| 14 | * |
| 15 | * |
| 16 | * |
| 17 | * |
| 18 | GND |
| 19 | HALL A |
| 20 | HALL B |
| 21 | HALL C |
| 22 | HOME |
| 23 | * |
| 24 | * |
| 25 | * |
| 26 |  |
| Reserved |  |
|  |  |
| 12 |  |
| 12 |  |

Electrical Pinout


| Motor Connector (DSUB9 MALE) |  |
| :--- | :--- |
| PIN | NAME |
| 1 | ${ }^{*}$ |
| 2 | ${ }^{*}$ |
| 3 | ${ }^{*}$ |
| 4 | ${ }^{*}$ |
| 5 | PHASE A |
| 6 | PHASE B |
| 7 | PHASE C |
| 8 | $*$ |
| 9 |  |
| * Reserved |  |

## LM2-300-BS-A-H-S-F-00

| Motor Specifications |  |
| :--- | :--- |
| Motor Type | $3 \Phi$ Brushless DC |
| BEMF Constant (V/KRPM) | 1.88 |
| Electrical Time Constant (ms) | 0.38 |
| Max Bus Voltage (VDC) | 24 |
| Max Continuous Current (A) | 3.0 |
| Motor Force Constant (N/A) | 50.8 |
| Peak Current (A) | 10.0 |
| Pin to Pin Inductance (mH) | 0.55 |
| Pin to Pin Resistance (ohm) | 1.51 |
| Poles per Revolution | 6 |


| Feedback Specifications | $5.0 \pm 10 \%$ |
| :--- | :--- |
| Supply Voltage (V) | 250 |
| Supply Current (mA) | Yes |
| Encoder Feedback | Incremental |
| Encoder Type | Square Wave Quadrature, RS-422 <br> compatible, A,B,Z, Differential Pairs |
| Encoder Ouput | 8000 cts/mm |
| Encoder Resolution | Open-Collector, No Pullup Resistor |
| Hall Switch Output | -20 |
| Hall Switch max current (mA) | Yes |
| Limit Switches | CMOS |
| Limit Switch Output Type | $\pm 20.0$ |
| Limit Switch Output current (mA) | Yes |
| Home Switch | CMOS |
| Home Switch Output Type | $\pm 20.0$ |
| Home Switch Output current (mA) |  |

A home switch is provided near center mechanical travel and a limit switch at each end of travel. The encoder will output one index pulse per revolution of the motor. This pulse is highly repeatable and can be used in coordination with the home switch to find an absolute position after power-up.

The limit switches will be pulled low throughout the travel range of the stage. The output will swing high at the end of travel and remain high until the mechanical limit of the stage is reached.

