



**Overview** 

## Precision Linear Motion Platform

#### **FEATURES**

- High speed
- 300mm Travel
- Precision ground ball screw drive
- Optical limit switches with home
- High resolution rotary encoder
- Recirculating ball linear ways
- Side seals
- Power-off brake



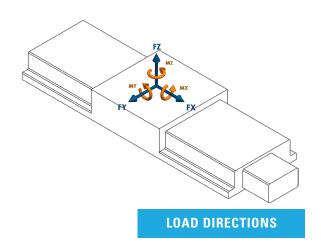
The LM3 Series stages are designed for a variety of applications. This compact low profile linear stage is built for high duty cycles and long life and attains high velocities for factory automation and semiconductor processing equipment. This stage has exceptional levels of accuracy, repeatability, flatness and straightness. Recirculating ball linear ways and the precision ground ball screw offer extremely smooth operation and velocity control. Side seals and a hard cover make it an excellent choice for dirty environments. The LM3 Series stages can be stacked to create XY motion. This LM3 model includes power-off brake.



## **Motion Specifications**

# **Product Specifications**

Encoder Output	A quad B, index
Force X (N)	200
Force Y (N)	200
Force Z (N)	440
Flatness (µm)	10
Height (mm)	62
Length (mm)	626
Limit Switches	Yes
Linear Accuracy (µm)	25
Linear Encoder Resolution (µm)	0.125
Linear Repeatability (µm)	2
Linear Velocity (mm/s)	150
Moment X (N·m)	50
Moment Y (N·m)	50
Moment Z (N·m)	25
Moving Mass X (kg)	1.79
Pitch +/- (arc-sec)	15
Screw Lead (mm)	2
Stage Mass (kg)	8.10
Straigtness (µm)	10
Width (mm)	165
Yaw +/- (arc-sec)	10

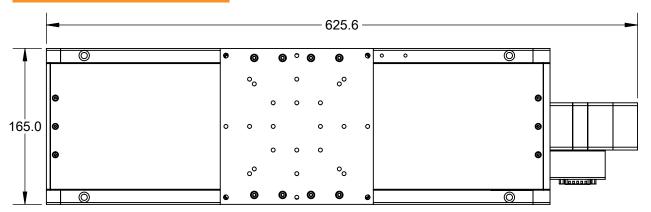


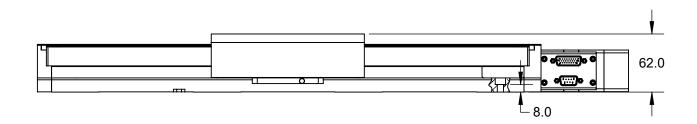
# Part Number Description

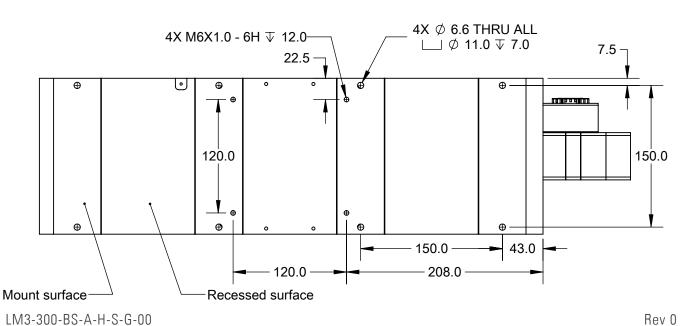
LM3	LM3 Series
300	300mm Travel
BS	Ball Screw Drive
А	Brushless Servo Motor
Н	0.125µm Rotary
S	Standard Precision
G	Side Seals and Brake
00	Standard Product (Call for custom)



## **Mechanical Specifications**

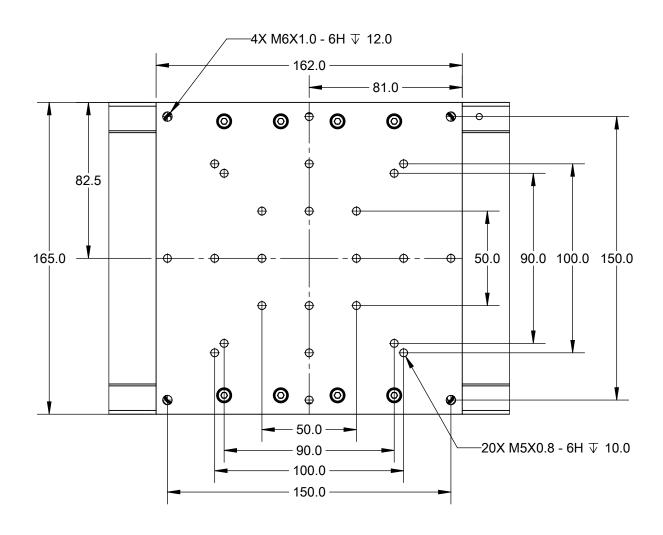








## **Mounting Pattern**

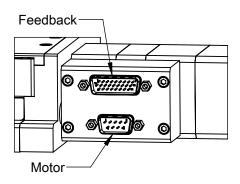






### **Electrical Pinout**

Feedback Connector (DSUB26HD MALE)	
PIN	NAME
1	+5V
2	A+
3	B+
4	RI+
5	LIM+
6	*
7	*
8	*
9	*
10	*
11	A-
12	B-
13	RI-
14	LIM-
15	*
16	*
17	*
18	*
19	GND
20	HALL A
21	HALL B
22	HALL C
23	HOME
24	*
25	*
26	*
* Reserved	



Motor Connector (DSUB9 MALE)	
PIN	NAME
1	*
2	*
3	*
4	BRAKE +
5	BRAKE -
6	PHASE A
7	PHASE B
8	PHASE C
9	*
* Reserved	



## **Electrical Specifications**

Motor Specifications		
Motor Type	3 Φ Brushless DC	
BEMF Constant (V/KRPM)	1.88	
Electrical Time Constant (ms)	0.38	
Max Bus Voltage (VDC)	24	
Max Continuous Current (A)	3.0	
Motor Force Constant (N/A)	50.8	
Peak Current (A)	10.0	
Pin to Pin Inductance (mH)	0.55	
Pin to Pin Resistance (ohm)	1.51	
Poles per Revolution	6	

Brake Specifications	
Brake Type	Power Off Engaged
Winding Voltage (VDC)	24.0
Winding Current (A)	0.17
Winding Resistance (Ohm)	138

Feedback Specifications		
Supply Voltage (V)	5.0±10%	
Supply Current (mA)	250	
Encoder Feedback	Yes	
Encoder Type	Incremental	
Encoder Ouput	Square Wave Quadrature, RS-422 compatible, A,B,Z, Differential Pairs	
Encoder Resolution	8000 cts/mm	
Hall Switch Output	Open-Collector, No Pullup Resistor	
Hall Switch max current (mA)	-20	
Limit Switches	Yes	
Limit Switch Output Type	CMOS	
Limit Switch Output current (mA)	±20.0	
Home Switch	Yes	
Home Switch Output Type	CMOS	
Home Switch Output current (mA)	±20.0	

A home switch is provided near center mechanical travel and a limit switch at each end of travel. The encoder will output one index pulse per revolution of the motor. This pulse is highly repeatable and can be used in coordination with the home switch to find an absolute position after power-up.

The limit switches will be pulled low throughout the travel range of the stage. The output will swing high at the end of travel and remain high until the mechanical limit of the stage is reached.