

Overview

Precision Linear Motion Platform

FEATURES

- Compact Low-Profile Design
- 100mm Travel
- Zero backlash, precision ground

ball screws

- Optical limit switches with home
- High resolution rotary encoder
- Brushless servo motor drive
- Crossed Roller Bearings



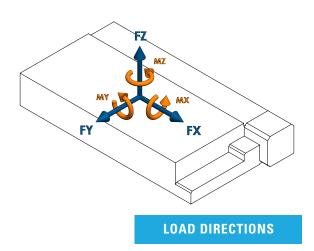
The LNS-BS Series stages are designed for a variety of applications. This compact low profile ball screw stage is built for high duty cycles and long life and can attain high velocities for factory automation and semiconductor processing equipment. This stage has exceptional levels of accuracy, repeatability, flatness and straightness. The crossed roller bearings and a precision ground ball screw offer extremely smooth operation and velocity control. The LNS-BS Series stages can be stacked to create X, Y and Z motion. The stage can operate in any orientation and has an optional brake for added safety.



Motion Specifications

Product Specifications

Encoder Output	A quad B, index
Force X (N)	200
Force Y (N)	250
Force Z (N)	500
Flatness (µm)	5
Height (mm)	45
Length (mm)	255
Limit Switches	Yes
Linear Accuracy (µm)	12
Linear Encoder Resolution (µm)	0.125
Linear Repeatability (µm)	2
Linear Velocity (mm/s)	150
Moment X (N⋅m)	60
Moment Y (N·m)	275
Moment Z (N·m)	110
Moving Mass X (kg)	1.67
Pitch +/- (arc-sec)	10
Screw Lead (mm)	2
Stage Mass (kg)	3.67
Straigtness (µm)	5
Width (mm)	155
Yaw +/- (arc-sec)	10

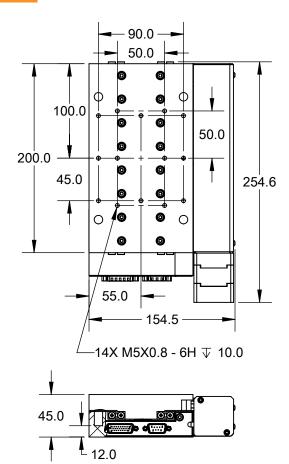


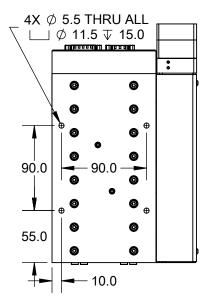
Part Number Description

LNS	LNS Series
100	100mm Travel
BS	Ball Screw Drive
А	Brushless Servo Motor
Н	0.125µm Rotary
S	Standard Precision
0	No Additional Options
00	Standar Product (Call for custom)



Mechanical Specifications



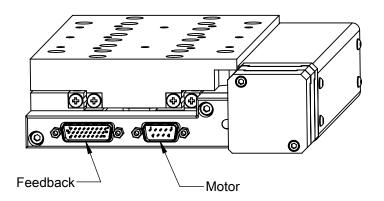






Electrical Pinout

Feedback Connector (DSUB26HD MALE)	
PIN	NAME
1	+5V
2	A+
3	B+
4	RI+
5	LIM+
6	*
7	*
8	*
9	*
10	*
11	A-
12	B-
13	RI-
14	LIM-
15	*
16	*
17	*
18	*
19	GND
20	HALL A
21	HALL B
22	HALL C
23	HOME
24	*
25	*
26	*
* Reserved	



Motor Connector (DSUB9 MALE)		
PIN	NAME	
1	*	
2	*	
3	*	
4	*	
5	*	
6	PHASE A	
7	PHASE B	
8	PHASE C	
9	*	
* Reserved		



Electrical Specifications

Motor Specifications		
Motor Type	3 Ф Brushless DC	
BEMF Constant (V/KRPM)	1.88	
Electrical Time Constant (ms)	0.38	
Max Bus Voltage (VDC)	24	
Max Continuous Current (A)	3.0	
Motor Force Constant (N/A)	50.8	
Peak Current (A)	10.0	
Pin to Pin Inductance (mH)	0.55	
Pin to Pin Resistance (ohm)	1.51	
Poles per Revolution	6	

Feedback Specifications		
Supply Voltage (V)	5.0±10%	
Supply Current (mA)	250	
Encoder Feedback	Yes	
Encoder Type	Incremental	
Encoder Ouput	Square Wave Quadrature, RS-422 compatible, A,B,Z, Differential Pairs	
Encoder Resolution	8000 cts/mm	
Hall Switch Output	Open-Collector, No Pullup Resistor	
Hall Switch max current (mA)	-20	
Limit Switches	Yes	
Limit Switch Output Type	CMOS	
Limit Switch Output current (mA)	±20.0	
Home Switch	Yes	
Home Switch Output Type	CMOS	
Home Switch Output current (mA)	±20.0	

A home switch is provided near center mechanical travel and a limit switch at each end of travel. The encoder will output one index pulse per revolution of the motor. This pulse is highly repeatable and can be used in coordination with the home switch to find an absolute position after power-up.

The limit switches will be pulled low throughout the travel range of the stage. The output will swing high at the end of travel and remain high until the mechanical limit of the stage is reached.